



A legfrissebb szakirodalmi források

Szakirodalmi ajánló robotika, robottechnológia témakörben

2019/2. sz. hírlevél

Open access források

Andrew Tzer-Yeu Chen, et al. : [Robust Computer Vision Chess Analysis and Interaction with a Humanoid Robot](#) (2019)

DOI: 10.3390/computers8010014

(Adatbázis: DOAJ)

Antonio Chella, et al. : [Editorial: Consciousness in Humanoid Robots](#) (2019)

DOI: 10.3389/frobt.2019.00017

(Adatbázis: DOAJ)

Elf Schellen; Agnieszka Wykowska: [Intentional Mindset Toward Robots—Open Questions and Methodological Challenges](#) (2019)

DOI: 10.3389/frobt.2018.00139

(Adatbázis: DOAJ)

Uwe Jahn, et al. : [Concepts of a Modular System Architecture for Distributed Robotic Systems](#) (2019)

DOI: 10.3390/computers8010025

(Adatbázis: DOAJ)

Ning Tan, et al. : [Inspiration From Games and Entertainment Artifacts: A Rising Paradigm for Designing Mechanisms and Algorithms in Robotics](#) (2019)

DOI: 10.3389/frobt.2019.00003

(Adatbázis: DOAJ)



Pekko Jaatinen, et al. : [Control System Commissioning of Fully Levitated Bearingless Machine](#) (2019)

DOI: 10.4173/mic.2019.1.3

(Adatbázis: DOAJ)

Mikhail Nikabadze, et al. : [Some Applications of Eigenvalue Problems for Tensor and Tensor–Block Matrices for Mathematical Modeling of Micropolar Thin Bodies](#) (2019)

DOI: 10.3390/mca24010033

(Adatbázis: DOAJ)

Források az előfizetett adatbázisokból

Az előfizetett adatbázisok elérése az Óbudai Egyetem hálózatából, automatikus IP cím azonosítással történik. Az egyes adatbázisok távoli elérésével, otthoni használatával kapcsolatban keresse az Egyetemi Könyvtár munkatársait.

Abiri, Ahmad, et al. : [Multi-Modal Haptic Feedback for Grip Force Reduction in Robotic Surgery](#) (2019)

DOI: 10.1038/s41598-019-40821-1

(Adatbázis: ProQuest)

Walker, Benjamin J, et al. : [Automated identification of flagella from videomicroscopy via the medial axis transform](#) (2019)

DOI: 10.1038/s41598-019-41459-9

(Adatbázis: ProQuest)

McBride, Kate E, et al. : [Knowledge and attitudes of theatre staff prior to the implementation of robotic-assisted surgery in the public sector](#) (2019)

DOI: 10.1371/journal.pone.0213840

(Adatbázis: ProQuest)



Lipkas, Julius; Deep, Kamal; Yao, Wei: [Robotic-Assisted 3D Bio-printing for Repairing Bone and Cartilage Defects through a Minimally Invasive Approach](#) (2019)

DOI: 10.1038/s41598-019-38972-2

(Adatbázis: ProQuest)

Wang, Ziheng, et al. : [Deep Learning with Convolutional Neural Network for Objective Skill Evaluation in Robot-assisted Surgery](#) (2019)

DOI: 10.1007/s11548-018-1860-1

(Adatbázis: ProQuest)

MacDonell, Jacquelyn: [Magnetic Resonance Guided Robotically Assisted Interstitial Focused Ultrasound in a Swine Model](#) (2020)

DOI: -

(Adatbázis: ProQuest)

Polechoński, Jacek, et al. : [Applicability of Smartphone for Dynamic Postural Stability Evaluation](#) (2019)

DOI: 10.1155/2019/9753898

(Adatbázis: EBSCOhost)

Wan, Peng, et al. : [An algorithm to optimize deployment of charging base stations for WRSN](#) (2019)

DOI: 10.1186/s13638-019-1393-5

(Adatbázis: EBSCOhost)

Nogueira, Daniel, et al. : [Comparing classification techniques for identification of grasped objects](#) (2019)

DOI: 10.1186/s12938-019-0639-0

(Adatbázis: EBSCOhost)





Guo, Kai, et al. : [UAV Sensor Fault Detection Using a Classifier without Negative Samples: A Local Density Regulated Optimization Algorithm](#) (2019)

DOI: 10.3390/s19040771

(Adatbázis: EBSCOhost)

Qi Zhang: [Web-based medical data visualization and information sharing towards application in distributed diagnosis](#) (2019)

DOI: 10.1016/j.imu.2018.10.010

(Adatbázis: Science Direct)

Moon G. Joo: [A controller comprising tail wing control of a hybrid autonomous underwater vehicle for use as an underwater glider](#) (2019)

DOI: 10.1016/j.ijnaoe.2019.03.001

(Adatbázis: Science Direct)

Shawn M. Walsh, et al. : [Approaching robotics and autonomous systems as an integrated materials, energy, and control problem](#) (2019)

DOI: 10.1016/B978-0-08-102260-3.09988-1

(Adatbázis: Science Direct)

Aitor Almeida, et al. : [A critical analysis of an IoT—aware AAL system for elderly monitoring](#) (2019)

DOI: 10.1016/j.future.2019.03.019

(Adatbázis: Science Direct)

Payam Abrishami, et al. : [When the Evidence Basis Breeds Controversies: Exploring the Value Profile of Robotic Surgery Beyond the Early Introduction Phase](#) (2019)

DOI: 10.1177/1077558719832797

(Adatbázis: SAGE journals)



Yoshitsugu Nakamura, et al. : [Left Internal Thoracic Artery Graft Assessment by Firefly Fluorescence Imaging for Robot-Assisted Minimally Invasive Direct Coronary Artery Bypass](#) (2019)

DOI: 10.1177/1556984519836810

(Adatbázis: SAGE journals)

Yunhan Lin, et al. : [Automatic sorting system for industrial robot with 3D visual perception and natural language interaction](#) (2019)

DOI: 10.1177/0020294018819552

(Adatbázis: SAGE journals)

XW Chen, et al. : [Response of bimetals with interfacial tension subjected to axisymmetric body force](#) (2019)

DOI: 10.1177/1081286518820086

(Adatbázis: SAGE journals)