



A legfrissebb szakirodalmi források

Szakirodalmi ajánló robotika, robottechnológia témakörben

2019/3. sz. hírlevél

Open access források

Chengyu Liu; Lung-Kwang Pan: [Advances in minimally invasive surgery and clinical measurement](#) (2019)

DOI: 10.1080/24699322.2018.1560103

(Adatbázis: Taylor & Francis Online)

Poramate Manoonpong; Christian Tetzlaff: [Neural Computation in Embodied Closed-Loop Systems for the Generation of Complex Behavior: From Biology to Technology](#) (2018)

278 p.

DOI: -

(Adatbázis: DOAB – Frontiers Spotlight)

Toshio Fukuda (Ed); Fei Chen (Ed); Qing Shi (Ed): [Bio-Inspired Robotics](#) (2018)

554 p.

DOI: 10.3390/books978-3-03897-046-0

(Adatbázis: DOAB – MDPI Books)

Bei Yang; Xi Wang; Penghui Sun: [Non-affine parameter dependent LPV model and LMI based adaptive control for turbofan engines](#) (2019)

DOI: 10.1016/j.cja.2018.12.031

(Adatbázis: DOAJ – Science Direct)



Alex Ellery: [Tutorial Review on Space Manipulators for Space Debris Mitigation](#) (2019)

DOI: 10.3390/robotics8020034

(Adatbázis: DOAJ – MDPI Robotics)

Olivér Törő; et al. : [Sensitivity and Performance Evaluation of Multiple-Model State Estimation Algorithms for Autonomous Vehicle Functions](#) (2019)

DOI: 10.1155/2019/7496017

(Adatbázis: DOAJ – Hindawi)

Madeleine Clare Elish: [Moral Crumple Zones: Cautionary Tales in Human-Robot Interaction](#) (2019)

DOI: 10.17351/ests2019.260

(Adatbázis: DOAJ)

Mare Srbinovska; et al. : [Optimization Methods for Energy Consumption Estimation in Wireless Sensor Networks](#) (2019)

DOI: 10.13044/j.sdewes.d6.0244

(Adatbázis: DOAJ)

Yu-Hsien Lin; et al. : [Development of an Image Processing Module for Autonomous Underwater Vehicles through Integration of Visual Recognition with Stereoscopic Image Reconstruction](#) (2019)

DOI: 10.3390/jmse7040107

(Adatbázis: DOAJ - MDPI JMSE)

Julian Hoth, et al. : [Determination of Flow Parameters of a Water Flow Around an AUV Body](#) (2019)

DOI: 10.3390/robotics8010005

(Adatbázis: DOAJ - MDPI Robotics)



Guanxue Wang; et al. : [Fuzzy Iterative Sliding Mode Control Applied for Path Following of an Autonomous Underwater Vehicle with Large Inertia](#) (2019)

DOI: 10.1155/2019/8650243

(Adatbázis: DOAJ – Hindawi)

Források az előfizetett adatbázisokból

Az előfizetett adatbázisok elérése az Óbudai Egyetem hálózatából, automatikus IP cím azonosítással történik. Az egyes adatbázisok távoli elérésével, otthoni használatával kapcsolatban keresse az Egyetemi Könyvtár munkatársait.

Samadiani, Najmeh: [A Review on Automatic Facial Expression Recognition Systems Assisted by Multimodal Sensor Data](#) (2019)

DOI: 10.3390/s19081863

(Adatbázis: EBSCOhost)

De la Torre, Gabriel G; et al. : [Wireless Computer-Supported Cooperative Work: A Pilot Experiment on Art and Brain–Computer Interfaces](#) (2019)

DOI: 10.3390/brainsci9040094

(Adatbázis: EBSCOhost)

Bissoli, Alexandre; et al. : [A Human–Machine Interface Based on Eye Tracking for Controlling and Monitoring a Smart Home Using the Internet of Things](#) (2019)

DOI: 10.3390/s19040859

(Adatbázis: EBSCOhost)

Mattias Appelgren: [Teaching Agents Through Correction](#) (2019)

DOI: -

(Adatbázis: ACM Digital Library)



Pierre Thalamy; Benoit Piranda; Julien Bourgeois: [Distributed Self-Reconfiguration using a Deterministic Autonomous Scaffolding Structure](#) (2019)

DOI: -

(Adatbázis: ACM Digital Library)

Tesca Fitzgerald, et al. : [Human-guided Trajectory Adaptation for Tool Transfer](#) (2019)

DOI: -

(Adatbázis: ACM Digital Library)

Yi-Fan Li; et al. : [Predicting pregnancy using large-scale data from a women's health tracking mobile application](#) (2019)

DOI: -

(Adatbázis: ACM Digital Library)

Errol R. Hoffmann; Colin G. Drury: [Models of the effect of teleoperation transmission delay on robot movement time](#) (2019)

DOI: 10.1080/00140139.2019.1612954

(Adatbázis: Taylor & Francis Online)

Jaesung Oh; et al. : [Real-time humanoid whole-body remote control framework for imitating human motion based on kinematic mapping and motion constraints](#) (2019)

DOI: 10.1080/01691864.2019.1581658

(Adatbázis: Taylor & Francis Online)



Nyomtatott folyóiratcikkek az Egyetemi Könyvtár állományából

Wolfgang Holub: Roboter mit Röntgenblick. In: QZ Qualität und Zuverlässigkeit 2019; 64(4); 56-60.

Sepúlveda, Johanna; Wilgerodt, Felix; Pehl, Michael: Towards memory integrity and authenticity of multi-processors system-on-chip using physical unclonable functions. In: it - Information Technology 2019; 61(1); 29-43.

DOI: 10.1515/itit-2018-0030

Goil, Mehran; et al. : Security validation of VP-based SoCs using dynamic information flow tracking. In: it - Information Technology 2019; 61(1); 45-58.

DOI: 10.1515/itit-2018-0027

Fischer, Viktor; Bernard, Florent; Bochart, Nathalie: Modern random number generator design – Case study on a secured PLL-based TRNG. In: it - Information Technology 2019; 61(1); 3-13.

DOI: 10.1515/itit-2018-0025

Nestler, Simon: Safety-critical human computer interaction. In: it - Information Technology 2019; 61(1); 67-70.

DOI: 10.1515/itit-2018-0037