

A legfrissebb szakirodalmi források

Óbudai Egyetem Egyetemi Könyvtár

Szakirodalmi ajánló robotika, robottechnológia témakörben

2019/4 sz. hírlevél

Open access források

Marouf, Ahmed A; et al.: [A Machine Learning based Approach for Mapping Personality Traits and Perceived Stress Scale of Undergraduate Students](#) (2019)

DOI: 10.5815/ijmeecs.2019.08.05

(Adatbázis: ProQuest)

Ceccarelli, Marco, Gasparetto, Alessandro (Ed.): [Mechanism Design for Robotics](#) (2019)

212 p.

DOI: 10.3390/books978-3-03921-059-6

(Adatbázis: DOAB – MDPI Books)

Giandomenico Spezzano (Ed.): [Swarm Robotics](#) (2019)

310 p.

DOI: 10.3390/books978-3-03897-923-4

(Adatbázis: DOAB – MDPI Books)

Botti, Vicent; Omicini, Andrea; Mariani, Stefano, Julian, Vicente: [Multi-Agent Systems](#) (2019)

392 p.

DOI: 10.3390/books978-3-03897-925-8

(Adatbázis: DOAB – MDPI Books)

Carlotta Patrone; et al.: [Development of a smart post-hospitalization facility for older people by using domotics, robotics, and automated tele-monitoring](#) (2019)

DOI: 10.4081/gc.2019.8122

(Adatbázis: DOAJ – page press)

Mais Yasen; et al.: [A systematic review on hand gesture recognition techniques, challenges and applications](#) (2019)

DOI: 10.7717/peerj-cs.218

(Adatbázis: DOAJ)

Ivan Soukal, et al.: [Novel Interaction Cost Analysis Applied to Bank Charges Calculator](#) (2019)

DOI: 10.3390/computers8030064

(Adatbázis: DOAB – MDPI)

Kyohei Tatsukawa; et al.: [Android Pretending to Have Similar Traits of Imagination as Humans Evokes Stronger Perceived Capacity to Feel](#) (2019)

DOI: 10.3389/frobt.2019.00088

(Adatbázis: DOAJ – Frontiers)

Loris Roveda; et al.: [Assisting Operators in Heavy Industrial Tasks: On the Design of an Optimized Cooperative Impedance Fuzzy-Controller With Embedded Safety Rules](#) (2019)

DOI: 10.3389/frobt.2019.00075

(Adatbázis: DOAJ – Frontiers)

Yanan Li; et al.: [Robotic Impedance Learning for Robot-Assisted Physical Training](#) (2019)

DOI: 10.3389/frobt.2019.00078

(Adatbázis: DOAJ – Frontiers)

Luiza Mici; German I. Parisi; Stefan Wermter: [Compositional Learning of Human Activities With a Self-Organizing Neural Architecture](#) (2019)

DOI: 10.3389/frobt.2019.00072

(Adatbázis: DOAJ – Frontiers)

Kovács Lehel István: [Gesture-Driven LEGO robots](#) (2019)

DOI: 10.2478/ausi-2019-0006

(Adatbázis: DOAJ – Sciendo)

Daniel Andre Duecker; et al.: [Learning Environmental Field Exploration with Computationally Constrained Underwater Robots: Gaussian Processes Meet Stochastic Optimal Control](#) (2019)

DOI: 10.3390/s19092094

(Adatbázis: DOAJ – MDPI)

Irene Rivas-Blanco; et al.: [Transferring Know-How for an Autonomous Camera Robotic Assistant](#) (2019)

DOI: 10.3390/electronics8020224

(Adatbázis: DOAJ – MDPI)

Források az előfizetett adatbázisokból

Az előfizetett adatbázisok elérése az Óbudai Egyetem hálózatából, automatikus IP cím azonosítással történik. Az egyes adatbázisok távoli elérésével, otthoni használatával kapcsolatban keresse az Egyetemi Könyvtár munkatársait.

Saad, N M; et al.: [Automated medical surgical trolley](#) (2019)

DOI: 10.11591/ijece.v9i3

(Adatbázis: ProQuest)

Marouf, Ahmed A; et al.: [A Machine Learning based Approach for Mapping Personality Traits and Perceived Stress Scale of Undergraduate Students](#) (2019)

DOI: 10.5815/ijmeccs.2019.08.05

(Adatbázis: ProQuest)

Lyu, Mingxing; et al.: [Development of an EMG-Controlled Knee Exoskeleton to Assist Home Rehabilitation in a Game Context](#) (2019)

DOI: 10.3389/fnbot.2019.00067

(Adatbázis: ProQuest)

Gunning, David; Aha, David W.: [DARPA's Explainable Artificial Intelligence Program](#) (2019)

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(Adatbázis: ProQuest)

Shi, Bin; et al.: [Wearable Ankle Robots in Post-stroke Rehabilitation of Gait: A Systematic Review](#) (2019)

DOI: 10.3389/fnbot.2019.00063

(Adatbázis: ProQuest)

Cler, Gabriel J; et al.: [Optimized and Predictive Phonemic Interfaces for Augmentative and Alternative Communication](#) (2019)

DOI: 10.1044/2019_JSLHR-S-MS18-18-0187

(Adatbázis: ProQuest)

Martínez-Rodrigo, Arturo; et al.: [Multi-Lag Analysis of Symbolic Entropies on EEG Recordings for Distress Recognition](#) (2019)

DOI: 10.3389/fninf.2019.00040

(Adatbázis: ProQuest)

Bergström, J; Hornbaek, K: [Human-Computer Interaction on the Skin](#) (2019)

DOI: 10.1145/3332166

(Adatbázis: EBSCOhost)

Liebergessell, Alex: [Design in the Age of Autonomous Machines: Modeling Inclusion, Dialogue, and Behavior](#) (2019)

DOI: 10.18848/1832-3669/cgp/v15i01

(Adatbázis: EBSCOhost)

Dokumentumok az Óbudai Egyetem Digitális Archívumából (ÓDA)

János Somló: [General Triangle Parallel Robot \(GTPR\) Basic Features of a New Robot Type -Kinematics and related Application Issues](#) (2019)

DOI: 10.12700/APH.16.5.2019.5.1

Mirosław Smieszek; Paweł Dobrzański; Magdalena Dobrzańska: [Comparison of the Level of Robotisation in Poland and Selected Countries, including Social and Economic Factors](#) (2019)

DOI: 10.12700/APH.16.4.2019.4.10