

A legfrissebb szakirodalmi források

Óbudai Egyetem Egyetemi Könyvtár

Szakirodalmi ajánló robotika, robottechnológia témakörben

2020/2. sz. hírlevél

Open access források

Hanaa Mohsin Ahmed: [Mobile-based Telemedicine Application using SVD and F-XoR Watermarking for Medical Images](#)

DOI: 10.21123/bsj.2020.17.1.0178

(Adatbázis: DOAJ)

F. A. Allaert; et al.: [Will applications on smartphones allow a generalization of telemedicine?](#) (2020)

DOI: 10.1186/s12911-020-1036-0

(Adatbázis: DOAJ - SpringerLink)

J. F. M. van den Heuvel; et al.: [Home-based telemonitoring versus hospital admission in high risk pregnancies: a qualitative study on women's experiences](#) (2020)

DOI: 10.1186/s12884-020-2779-4

(Adatbázis: DOAJ - SpringerLink)

Onder Erin, et al.: [Magnetic Resonance Imaging System–Driven Medical Robotics](#) (2020)

DOI: 10.1002/aisy.201900110

(Adatbázis: DOAJ – Wiley Online Library)

Sangkyu Lee; et al.: [A Skin-Conformal, Stretchable, and Breathable Fiducial Marker Patch for Surgical Navigation Systems](#) (2020)

DOI: 10.3390/mi11020194

(Adatbázis: DOAJ – MDPI)

Liang Qiu; et al.: [Real-time surgical instrument tracking in robot-assisted surgery using multi-domain convolutional neural network](#) (2020)

DOI: 10.1049/htl.2019.0068

(Adatbázis: DOAJ – IET Digital Library)

Jian Zhang; et al.: [RFHUI: an RFID based human-unmanned aerial vehicle interaction system in an indoor environment](#) (2020)

DOI: 10.1016/j.dcan.2019.05.001

(Adatbázis: DOAJ – Science Direct)

Xue Fan; Henry Markram: [A Brief History of Simulation Neuroscience](#) (2019)

DOI: 10.3389/fninf.2019.00032

(Adatbázis: DOAJ – Frontiers)

Andreas B. Martinsen; et al.: [Reinforcement Learning-Based Tracking Control of USVs in Varying Operational Conditions](#) (2020)

DOI: 10.3389/frobt.2020.00032

(Adatbázis: DOAJ – Frontiers)

Wenjin Wang, et al.: [A Fault-Tolerant Steering Prototype for X-Rudder Underwater Vehicles](#) (2020)

DOI: 10.3390/s20071816

(Adatbázis: MDPI)

Piotr Kaniewski: [Extended Kalman Filter with Reduced Computational Demands for Systems with Non-Linear Measurement Models](#) (2020)

DOI: 10.3390/s20061584

(Adatbázis: MDPI)

Manuel Vega-Heredia; et al.: [Multi-Sensor Orientation Tracking for a Façade-Cleaning Robot](#) (2020)

DOI: 10.3390/s20051483

(Adatbázis: MDPI)

Források az előfizetett adatbázisokból

Az előfizetett adatbázisok elérése az Óbudai Egyetem hálózatából, automatikus IP cím azonosítással történik. Az egyes adatbázisok távoli elérésével, otthoni használatával kapcsolatban keresse az Egyetemi Könyvtár munkatársait.

Hakoköngäs, Eemeli; Asiala, Anna: [Image of the Human in Service Design: An Interview-Based Case Study](#) (2020)

DOI: -

(Adatbázis: EBSCOhost)

Benitez-Garcia, Gibran; et al.: [Finger Gesture Spotting from Long Sequences Based on Multi-Stream Recurrent Neural Networks](#) (2020)

DOI: 10.3390/s20020528

(Adatbázis: EBSCOhost)

De la Iglesia, Daniel H; et al.: [Connected Elbow Exoskeleton System for Rehabilitation Training Based on Virtual Reality and Context-Aware](#) (2020)

DOI: 10.3390/s20030858

(Adatbázis: EBSCOhost)

Cardona, Manuel; et al.: [ALICE: Conceptual Development of a Lower Limb Exoskeleton Robot Driven by an On-Board Musculoskeletal Simulator](#) (2020)

DOI: 10.3390/s20030789

(Adatbázis: EBSCOhost)

Budiyanta, Nova Eka; Sereati, Catherine Olivia; Lukas: [P-D controller computer vision and robotics integration based for student's programming comprehension improvement](#) (2020)

DOI: 10.12928/TELKOMNIKA.v18i2.14881

(Adatbázis: EBSCOhost)

Cumpanas, Alin Adrian, et al.: [Does sleep deprivation alter virtual reality-based robotic surgical skills?](#) (2020)

DOI: 10.5114/wiitm.2019.90565

(Adatbázis: EBSCOhost)

Ni, Jianjun; et al.: [An Improved Deep Residual Network-Based Semantic Simultaneous Localization and Mapping Method for Monocular Vision Robot](#) (2020)

DOI: 10.1155/2020/7490840

(Adatbázis: EBSCOhost)

Abbas, Tahir, et al.: [Crowd of Oz: A Crowd-Powered Social Robotics System for Stress Management](#) (2020)

DOI: 10.3390/s20020569

(Adatbázis: EBSCOhost)

Odry, Ákos; et al.: [A Novel Fuzzy-Adaptive Extended Kalman Filter for Real-Time Attitude Estimation of Mobile Robots](#) (2020)

DOI: 10.3390/s20030803

(Adatbázis: EBSCOhost)

Wu Jinhui; et al.: [A computational framework of kinematic accuracy reliability analysis for industrial robots](#) (2020)

DOI: 10.1016/j.apm.2020.01.005

(Adatbázis: Science Direct)

Haotian Yu, et al.: [Three-dimensional shape measurement technique for large-scale objects based on line structured light combined with industrial robot](#) (2020)

DOI: 10.1016/j.ijleo.2019.163656

(Adatbázis: Science Direct)

Hongyi Liu; Lihui Wang: [Remote human–robot collaboration: A cyber–physical system application for hazard manufacturing environment](#) (2020)

DOI: 10.1016/j.jmsy.2019.11.001

(Adatbázis: Science Direct)

Zhihao Liu; et al.: [Dynamic risk assessment and active response strategy for industrial human-robot collaboration](#) (2020)

DOI: 10.1016/j.cie.2020.106302

(Adatbázis: Science Direct)

Theo Lins; Ricardo Augusto Rabelo Oliveira: [Cyber-physical production systems retrofitting in context of industry 4.0](#) (2020)

DOI: 10.1016/j.cie.2019.106193

(Adatbázis: Science Direct)