

A legfrissebb szakirodalmi források

Óbudai Egyetem Egyetemi Könyvtár

Szakirodalmi ajánló robotika, robottechnológia témakörben

2020/3. sz. hírlevél

Open access források

Rojas Ferrer, César Daniel; et al.: [Read-the-game: System for skill-based visual exploratory activity assessment with a full body virtual reality soccer simulation](#) (2020)

DOI: 10.1371/journal.pone.0230042

(Adatbázis: EBSCOhost)

Chao-Ming, Yu; Yu-Hsien, Lin: [Experimental Analysis of a Visual-Recognition Control for an Autonomous Underwater Vehicle in a Towing Tank](#) (2020)

DOI: 10.3390/app10072480

(Adatbázis: Proquest)

Giuseppe S; Cozzella, L; Leccese, F: [Underwater Optical Wireless Communications: Overview](#) (2020)

DOI: 10.3390/s20082261

(Adatbázis: Proquest)

Hussein, Mohammed Khudhur; Khamiss, Nasser N: [Integrating millimeter wave with hybrid precoding multiuser massive MIMO for 5G communication](#) (2020)

DOI: 10.12928/TELKOMNIKA.v18i1.13674

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Kim, Dae Eun (ed): [Advanced Mobile Robotics: Volume 1](#) (2020)

468 p.

DOI: 10.3390/books978-3-03921-917-9

(Adatbázis: DOAB – MDPI Books)

Kim, Dae Eun (ed): [Advanced Mobile Robotics: Volume 2](#) (2020)

498 p.

DOI: 10.3390/books978-3-03921-945-2

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Kim, Dae Eun (ed): [Advanced Mobile Robotics: Volume 3](#) (2020)

270 p.

DOI: 10.3390/books978-3-03921-947-6

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Luis Payá; Oscar Reinoso Garcia (Eds): [Visual Sensors](#) (2020)

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DOI: 10.3390/books978-3-03928-339-2

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Lucian Stefanita Grigore; et al.: [The Integration of Collaborative Robot Systems and Their Environmental Impacts](#) (2020)

DOI: 10.3390/pr8040494

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Piotr Barosz; Grzegorz Gołda; Adrian Kampa: [Efficiency Analysis of Manufacturing Line with Industrial Robots and Human Operators](#) (2020)

DOI: 10.3390/app10082862

(Adatbázis: DOAJ – MDPI)

Ionel Zagan; et al.: [Design, Fabrication, and Testing of an IoT Healthcare Cardiac Monitoring Device](#) (2020)

DOI: 10.3390/computers9010015

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Vilém Novák; et al.: [Topology in the Alternative Set Theory and Rough Sets via Fuzzy Type Theory](#) (2020)

DOI: 10.3390/math8030432

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Baocang Ding; Xiaoming Tang; Jianchen Hu: [A Summary of Dynamic Output Feedback Robust MPC for Linear Polytopic Uncertainty Model with Bounded Disturbance](#) (2020)

DOI: 10.1155/2020/3830724

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Források az előfizetett adatbázisokból

Az előfizetett adatbázisok elérése az Óbudai Egyetem hálózatából, automatikus IP cím azonosítással történik. Az egyes adatbázisok távoli elérésével, otthoni használatával kapcsolatban keresse az Egyetemi Könyvtár munkatársait.

Silva Junior A.G.D; et al.: [High-Level Path Planning for an Autonomous Sailboat Robot Using Q-Learning](#) (2020)

DOI: 10.3390/s20061550

(Adatbázis: Embase – **elérhető 2020. június 5-ig próbáhozáférés keretében!**)

Amparore D; et al.: [Impact of the COVID-19 pandemic on urology residency training in Italy](#) (2020)

DOI: 10.23736/S0393-2249.20.03868-0

(Adatbázis: Embase – **elérhető 2020. június 5-ig próbáhozáférés keretében!**)

Feng Z; et al.: [Robotic-assisted adrenalectomy using da Vinci Xi vs. Si: are there differences?](#) (2020)

DOI: 10.1007/s11701-019-00995-2

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Eslamian S; Reisner L.A; Pandya A.K: [Development and evaluation of an autonomous camera control algorithm on the da Vinci Surgical System](#) (2020)

DOI: 10.1002/rcs.2036

(Adatbázis: Embase – **elérhető 2020. június 5-ig próbáhozáférés keretében!**)

Donnelly-Kehoe P; et al.: [Reliable local dynamics in the brain across sessions are revealed by whole-brain modeling of resting state activity](#) (2019)

DOI: 10.1002/hbm.24572

(Adatbázis: Embase – **elérhető 2020. június 5-ig próbáhozáférés keretében!**)

Ahmed, Shahzad; Sung Ho Cho: [Hand Gesture Recognition Using an IR-UWB Radar with an Inception Module-Based Classifier](#) (2020)

DOI: 10.3390/s20020564

(Adatbázis: EBSCOhost)

Irvine, Naomi; et al.: [Neural Network Ensembles for Sensor-Based Human Activity Recognition Within Smart Environments](#) (2020)

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Li, Yunwang; et al.: [Kinematic Modeling of a Combined System of Multiple Mecanum-Wheeled Robots with Velocity Compensation](#) (2020)

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De la Iglesia, Daniel H; et al.: [Connected Elbow Exoskeleton System for Rehabilitation Training Based on Virtual Reality and Context-Aware](#) (2020)

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Lee, Taesik; et al.: [Design and Control of a Polycentric Knee Exoskeleton Using an Electro-Hydraulic Actuator](#) (2020)

DOI: 10.3390/s20010211

(Adatbázis: EBSCOhost)

Zhou, Kun; Meng, Xiangxi; Cheng, Bo: [Review of Stereo Matching Algorithms Based on Deep Learning](#) (2020)

DOI: 10.1155/2020/8562323

(Adatbázis: EBSCOhost)

Schmidt, Charles H: [Into the Black Box: What Can Machine Learning Offer Environmental Health Research?](#) (2020)

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Bălan, Oana; et al.: [An Investigation of Various Machine and Deep Learning Techniques Applied in Automatic Fear Level Detection and Acrophobia Virtual Therapy](#) (2020)

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Zomarev, A; Rozhenko, M: [Impact of Self-driving Cars for Urban Development](#) (2020)

DOI: 10.17323/2500-2597.2020.1.70.84

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Zheng, J H; et al.: [Comparison and error analysis of off-design and design models of energy hubs](#) (2019)

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