

Szakirodalmi ajánló

Alkalmazott informatika

témakörben

2022/1. sz. hírlevél

Open access források

Duc Le Trung, et al.: [Involvement of the Rostromedial Prefrontal Cortex in Human-Robot Interaction: fNIRS Evidence From a Robot-Assisted Motor Task](#) (2022)

DOI: 10.3389/fnbot.2022.795079

(Adatbázis: DOAJ – Frontiers)

Jonathan Beaudoin, Thierry Laliberté and Clément Gosselin: [Inverse kinematics strategies for physical human-robot interaction using low-impedance passive link shells](#) (2022)

DOI: 10.1017/S0263574722001102

(Adatbázis: Cambridge University Press)

Carlos Calleja, Hadassah Drukarch, Eduard Fosch-Villaronga: [Harnessing robot experimentation to optimize the regulatory framing of emerging robot technologies](#) (2022)

DOI: 10.1017/dap.2022.12

(Adatbázis: Cambridge University Press)

W. Brandon Martin, Alexander Boehler et al.: [Development and testing of the aerial porter exoskeleton](#) (2022)

DOI: 10.1017/wtc.2021.18

(Adatbázis: Cambridge University Press)

Christine Linnenberg, Robert Weidner: [Industrial exoskeletons for overhead work: Circumferential pressures on the upper arm caused by the physical human-machine-interface](#) (2022)

DOI: 10.1016/j.apergo.2022.103706

(Adatbázis: ScienceDirect)

Hongyi Yuan, Lifeng Ma, et al.: [On-Chip Cascaded Bandpass Filter and Wavelength Router Using an Intelligent Algorithm](#) (2021)

DOI: 10.1109/JPHOT.2021.3100357

(Adatbázis: *IEEE Xplore*)

Dimitrios Boursinos, Xenofon Koutsoukos: [Assurance monitoring of learning-enabled cyber-physical systems using inductive conformal prediction based on distance learning](#) (2021)

DOI: 10.1017/S089006042100010X

(Adatbázis: *Cambridge University Press*)

Mangor Pedersen, Andrew Zalesky: [Intracranial brain stimulation modulates fMRI-based network switching](#) (2021)

DOI: 10.1016/j.nbd.2021.105401

(Adatbázis: *ScienceDirect*)

D.Venu, Babu J., et al.: [End-to-end security in embedded system for modern mobile communication technologies](#) (2022)

DOI: 10.1016/j.measen.2022.100393

(Adatbázis: *ScienceDirect*)

Amjad Ali, et al.: [High capacity chipless RFID tags for biomass tracking application](#) (2022)

DOI: 10.1017/S1759078722000745

(Adatbázis: *Cambridge University Press*)

He-Jun Lu, Yang Yu: [Research on WiFi Penetration Testing with Kali Linux](#) (2021)

DOI: 10.1155/2021/5570001

(DOAJ – *Hindawi*)

Albina Kamalova, Suk Gyu Lee, Soon Hak Kwon: [Occupancy Reward-Driven Exploration with Deep Reinforcement Learning for Mobile Robot System](#) (2022)

DOI: 10.3390/app12189249

(DOAJ – MDPI)

J. Ernesto Solanes, Adolfo Muñoz, Luis Gracia, Josep Tornero: [Virtual Reality-Based Interface for Advanced Assisted Mobile Robot Teleoperation](#) (2022)

DOI: 10.3390/app12126071

(DOAJ – MDPI)

Források az előfizetett adatbázisokból

Az előfizetett adatbázisok elérése az Óbudai Egyetem hálózatából, automatikus IP cím azonosítással történik. Az egyes adatbázisok távoli elérésével, otthoni használatával kapcsolatban a Könyvtár honlapján tájékozódhat a <http://lib.uni-obuda.hu/eisz-adatbazisok> oldalon. Ha kérdése van, keresse az Egyetemi Könyvtár munkatársait!

Petr Kadera, et al.: [Sub-THz Luneburg lens enabled wide-angle frequency-coded identification tag for passive indoor self-localization](#) (2022)

DOI: 10.1017/S175907872200054X

(Adatbázis: Cambridge University Press)

Kawther Mekki, et al.: [Investigation on the chipless RFID tag with a UWB pulse using a UWB IR-based reader](#) (2021)

DOI: 10.1017/S1759078721000313

(Adatbázis: Cambridge University Press)

Shahid Habib, et al.: [A low-profile FSS-based high capacity chipless RFID tag for sensing and encoding applications](#) (2021)

DOI: 10.1017/S1759078721000362

(Adatbázis: Cambridge University Press)

Eleni Tsalapati, et al.: [Enhancing RFID system configuration through semantic modelling](#) (2021)

DOI: 10.1017/S0269888921000096

(Adatbázis: Cambridge University Press)

Omkar A.Chittar, Shivprakash B.Barve, Vilas Kanthale: [Experimental investigations on waist supportive passive exoskeleton to improve human comfort](#) (2022)

DOI: 10.1016/j.matpr.2022.09.086

(Adatbázis: ScienceDirect)

Rushikesh Gholap, Sandeep Thorat, Abhijeet Chavan: [Review of current developments in lower extremity exoskeleton systems](#) (2022)

DOI: 10.1016/j.matpr.2022.09.056

(Adatbázis: ScienceDirect)

Weihai Chen, et al.: [Electromyography-controlled lower extremity exoskeleton to provide wearers flexibility in walking](#) (2022)

DOI: 10.1016/j.bspc.2022.104096

(Adatbázis: ScienceDirect)

Barolli, A., Bylykbashi, K., Qafzezi, E. et al.: [A hybrid intelligent system based on particle swarm optimization and distributed genetic algorithm for WMNs: a comparison study of boulevard and stadium distributions considering different router replacement methods and load balancing](#) (2022)

DOI: 10.1007/s11276-022-03050-5

(Adatbázis: Springer)

Raja Basha, A.: [A Review on Wireless Sensor Networks: Routing](#) (2022)

DOI: 10.1007/s11277-022-09583-4

(Adatbázis: Springer)

Harrabi, S., Jaafar, I.B. & Ghedira, K.: [Survey on IoV Routing Protocols](#) (2022)

DOI: 10.1007/s11277-022-09976-5

(Adatbázis: Springer)

Bhattacharjya, S., Saiedian, H. : [Establishing and validating secured keys for IoT devices: using P3 connection model on a cloud-based architecture](#) (2022)

DOI: 10.1007/s10207-021-00562-7

(Adatbázis: Springer)

Yu, H., Li, X., Fan, C. et al. : [MsDA: Multi-scale domain adaptation dehazing network](#) (2022)

DOI: 10.1007/s10489-022-03540-1

(Adatbázis: Springer)

Katsuhiko Nishizawa, Toru Tsumugiwa, Ryuichi Yokogawa: [Gait Rehabilitation and Locomotion Support System Using a Distributed Controlled Robot System](#) (2022)

DOI: 0.20965/jrm.2022.p0072

(Adatbázis: ProQuest)

Çatalbaş Bahadır; Morgül Ömer: [Two-Legged Robot Motion Control With Recurrent Neural Networks](#) (2022)

DOI: 10.1007/s10846-021-01553-5

(Adatbázis: ProQuest)

Narayan, Ashwin, et al.: [Real-Time Hierarchical Classification of Time Series Data for Locomotion Mode Detection](#) (2021)

DOI: 10.1109/JBHI.2021.3106110

(Adatbázis: IEEE Xplore)